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C++ Standard Template Library by Ranges^{*}

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Abstract

The C++ Standard Template Library (STL) is the most popular library based on the generic programming paradigm. STL is widely-used, because the library is part of the C++ Standard. It consists of many useful generic data structures and generic algorithms, that are fairly irrespective of the used container. Iterators bridge the gap between containers and algorithms. As a result of this layout the complexity of the library is greatly reduced and we can extend the library with new containers and algorithms simultaneously.

Iterators introduced many different problems. First, hard to write handcrafted iterators. Some people argue for the range types which can be a superior abstraction. Ranges can be aggregated in a better way. They have better checking abilities.

In this paper we present an overview about the differences between ranges and iterators. We examine a set of algorithms with ranges. Creating new range types is also considered.

Keywords: STL, iterators, ranges

MSC: 68N19 Other programming techniques

1. Introduction

The C++ Standard Template Library (STL) was developed by generic programming approach [7, 16]. In this way some containers defined as class templates and many algorithms can be implemented as function templates. Furthermore, algorithms are implemented in a container-independent way, so one can use them with different containers [20]. C++ STL is widely-used because it is a very useful, standard C++ library that contains many useful containers (like list, vector, map, etc.), many algorithms (like sort, find, count, etc.) among other utilities.

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The STL was designed to be extensible. We can add new containers that can work together with existing algorithms. On the other hand, we can extend the set of algorithms with a new one that can be work together with existing containers. Iterators bridge the gap between containers and algorithms [5]. STL also includes some adaptor types which transform standard elements of the library for a different functionality [1, 14].

However, the usage of C++ STL does not mean bugless or error-free code [9]. Contrarily, incorrect application of the library may introduce new types of problems [19]. One of the root causes is that algorithms take two iterators as the input interval. One range is passed by two objects. Parameters are handled independently and the connections between them are analyzed in a very difficult way.

This paper is organized as follows. Some known iterator-related problems are described in section 2. The notation of *ranges* is introduced and advantages of ranges are present in section 3. A range-based STL implementation can be found in section 4. After all, we conclude our results and give some directions about the future work in section 5.

2. General problems

Some problems come from the STL's generic approach. This approach prepossesses the software metrics [19]. In this section we present some typical STL-related mistakes.

One the most trivial problem is according to the algorithms' precondition [18]. For example, some algorithms need sorted input and they take advantage of sortedness, but input is not checked neighter at compilation time nor at runtime. Algorithms like binary_search, lower_bound, equal_range result in undefined behaviour when they called on an unsorted range. However, it is very difficult to check the input's sortedness without algorithm modification [13].

Another typical problem is related to the iterator invalidation [10]. This appears when a contiguous-memory container (for example, vector) reallocates itself when its capacity is full. We have constructed iterators before the reallocation, and use one of these iterators after the reallocation results in an undefined behaviour. Let us consider the following code snippet:

```
std::vector<int> v;
v.push_back(1);
std::vector<int>::iterator it = v.begin();
// vector's capacity changes:
for( int i = 0; i < 100; ++i)
  v.push_back(i);
int o = *it;
```

The main weakness of iterators that every algorithms take two iterators as one interval [4]. For instance, here are some declarations from the STL:

Another typical iterator related bug appears when one misuses output iterators:

```
std::vector<int> v;
v.push_back( 3 );
std::list<int> 1;
std::copy( v.begin(), v.end(), l.begin() );
```

The elements of the vector should be copied to the list in the previous code, but it causes runtime error. copy assumes that it can copy to the output, there is allocated memory, but in an empty list no one allocates space for the elements. It does not causes problem, if the list's size is not less than vector's size. back_inserter and front_inserter iterators can be used for to force push_back and push_front method, respectively.

In this section we described a set of problems which comes from the generic approach of the STL.

3. Ranges

Range is the abstraction over iterators. Ranges are introduced in the D programming language.

The simplest range is the notation of input ranges. Their interface can be defined in the following way:

```
template <class T>
class InputRange
{
    void pop_front();
    T& front();
    bool empty() const;
};
```

We can express the very same functionality with two input iterators and one input range in a different syntax. But as range is a type, one can check many properties. For instance, sorted range's constructor can test if the range is checked and it ensures the correct behaviour without algorithm modification.

A typical implementation for contiguous-memory range is the following:

```
template <class T>
class ContRange
ł
  T *first, *last;
public:
  bool empty() const
  ſ
    return first == last;
  }
  void pop_back()
  ł
    ++first;
  }
  T& front()
  Ł
    return *first;
  }
};
```

This way we can easily check range-related properties. For example, we can make sure if front is called on empty range:

```
T& front()
{
   assert( !empty() );
   return *first;
}
```

Call of algorithms with mixture of ranges is much more easier by ranges than by iterators. For instance, let us consider the following code fragment:

```
template <class R1, class R2>
R2 copy( R1 r1, R2 r2 );
std::vector<float> v;
std::list<int> s;
std::deque<double> d;
std::copy( chain( v, s ), d );
```

Let us consider a copy algorithm which copies the first to the second range and returns the untouched portion of r2, and we have a function called **chain** which returns a range which is the concatenation of the arguments. To describe this scenario in an STL-way is very difficult.

Iterator hierarchy is grouping of iterator based on iterators' capabilities. Iterator hierarchy cannot be appeared by language constructs [23], but it can appear by range types and inheritance.

One can easily implement an adaptor type, that reverses the traversal:

```
template<class R>
class Retro
ł
  Rr;
public:
  bool empty() const
  ſ
    return r.empty();
  }
  void pop_front()
  ſ
    return r.pop_back();
  }
  void pop_back()
  ł
     return r.pop_front();
  }
  E<R>::Type& front()
  {
    return r.back();
  }
  E<R>::Type& back()
  ſ
    return r.front();
  }
```

};

Iterators' advantage is the reverse-compatibility with the built-in arrays because of the pointer-arithmetic. Every standard algorithms work with arrays too.

In this section we present ranges' basic idea. We argue for ranges, because they support range-related properties that iterators cannot do among other advantages.

4. C++ Standard Template Library by Ranges

In this section we overview a potential implementation of the STL algorithms in which ranges can be used instead of iterators.

For instance, we can write our for_each algorithm in the following:

```
template <class Range, class Fun>
Fun for_each( Range r, Fun f )
{
   while ( !r.empty() )
   {
    f( r.front() );
    r.pop_front();
   }
}
```

This implementation is quite straightforward, because it takes two parameters: the range and a functor object to be called on the elements in the range.

There are some pitfalls with this implementation. In this implementation list and deque containers can be work as ranges, but vector is not allowed.

Every STL algorithms can be defined in this way too. It does not constraint the genericity of algorithms. The library is kept generic.

Usage of standard stream iterators are lengthy, uncomprehensible, unmaintenable. With the help of ranges these applications can be easier too. Let us consider the following two different implementations of the similar code which copies the standard input to standard output:

In this section we argue for ranges by present an STL implementation by ranges. Many algorithms can be called easier in this way.

5. Conclusion and Future Work

STL is widely-used generic library in which iterators play an important role. The STL itself introduces new potential errors based on the iterators. Unfortunately, these errors cannot handle in a non-intrusive way.

The ranges are an abstraction over iterators. The most important feature of ranges that properties can be checked in the range type. An other feature is the mixture of ranges. STL algorithms can be rewritten by ranges. Usage of algorithms can be easier especially when one deals with stream iterators.

Abstraction penalty occurs when ranges are used. Measuring the overhead of the runtime checks is necessary. In this paper we do not deal with *output ranges*. An elegant interface is necessary when output ranges are used.

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